

Camera Image Visualization meeting with IPAC

Dates: September 20-21 2016

Location: SLAC,

Tuesday: Tulara Conference Room, Bldg 53, Room 4006

Wednesday: Napa Conference Room, Bldg 41, Room 1158

Possible conflicts

- 10am Wednesday, CCB (Gregory)
- 11am Wednesday, TS8 meeting (Stuart, Tony)
- 1pm Wednesday, Tiger Team meeting (Tony, Gregory) – can be skipped

Tentative agenda for Wednesday::

10am: Initial discussion of image data flow API

11am: Stuart and Tony at TS8 meeting

1pm: Python binding/services/diagnostic cluster

3pm: Follow up on image data flow API

3:45pm: Summary and follow up actions

4pm: IPAC team leaves for airport

Action Items

- Make gliffy diagram of "yellow box" architecture including I&T diagnostic cluster [Stuart Marshall Gregory Dubois-Felsmann](#)
- Con Ops for the display – how/who/when for the camera visualization display [Jon Thaler \(TBC\) Stuart Marshall](#)
- Initial "yellow box" interface, and implementation using existing fits file reader [Trey Roby](#). This would then become a proposal for further discussion
- Minor fixes to build process, generate pure war, workaround duplicate nom.tam.fits classes, etc [Loi Ly](#)
- Proposal for support of "cropped image staging" for more efficient image passing to python [Trey Roby](#)
- Needs to be some way to tell firefly which "yellow box interface" to use to fetch image (can be handled via a request object)
- Once implementation of channels/request object/user defined actions is complete, provide demo/example [Trey Roby Tatiana Goldina](#)
- Add "back" button in addition to pause/resume immediate data interface so that can go back to previous image (in case you pushed the pause button just too late). Firefly already keeps a cache, so just going back to the previous URL should work.
- Expose ability to plot pre-binned histogram data, and add demo [Tatiana Goldina](#)
- At some point in the future generate a proposed timeline for delivery of new functionality [Xiuqin Wu](#)

Possible topics:

- Current plans for visualization/diagnostic cluster for I&T, including [data flow](#)
- Demo of integration of firefly with Camera functionality
- List of camera requirements
 - Front end
 - display cross multiple panels, layout of the image
 - one browser across multiple panels, one browser for each panel
 - speed of image refreshment
 - 15 seconds? Data is delivered in 2 seconds, so being able to display image in similar time should be goal
 - control image display (zoom, pan, stretch ...), on a monitor or iPad
 - where to display the action icons, only on monitor/iPad?
 - Raft, CCD, segment outline overlay on image
 - drill down from raft, to CCD, to segment
 - over-scan display
 - server side
 - stitch segments into CCD, CCDs into raft, parallel reading of 3 REBs?

- data flow from camera to Firefly server, EDF and raw data
 - over-scan representation
 - API for direct delivery of data to firefly (no FITS file)
 - Distributed backend
 - Smoother integration with python backend
- Issues with existing (old) Firefly
 - Overview of new Firefly functionality
 - Future directions for server